

Glentek's GMR4900 sseries of high performance, permanent magnet DC brush servo motors utilize high-energy Neodymium-Iron- Boron (NdFeB) magnets, which provide more torque in a smaller package with higher dynamic performance than traditional ferrite magnet designs. In addition, due to high torque to inertia ratio of these motors, they are ideal for applications which require high acceleration and deceleration characteristics or where the physical size of the motor is a major concern.

- Continuous Torque Range:
- 19.0 Lb-in (2.15 Nm) to 65.0 Lb-in (7.34 Nm)
- Peak Torque Range:

95.0 Lb-in (10.75 Nm) to 325.0 Lb-in (36.70 Nm)

## **GMR4900 SERIES FEATURES**

High-energy Neodymium-Iron-Boron (NdFeB) magnet design provides more torque in a smaller package with higher dynamic performance.

Skewed armature design provides ultra smooth operation (i.e. low cogging torque) at all speeds.

Various electrical windings are available as standard to suit both low and high voltage amplifiers in order to provide optimum speed and torque characteristics. Optional custom electrical windings are available to meet virtually any requirement.

Worldwide standard mounting configurations are available (Square, Round, NEMA 42, and NEMA 56C).

Optional custom mounting configurations are available to meet virtually any requirement.

Industry standard lead termination configurations. (i.e. MS connectors, fluid tight strain relief cable exit, NPT hole with flying leads and terminal boxes)

Optional industry standard feedback devices. (i.e. high performance silver commutator tachometers, and encoders)

Class H insulation standard.

Standard operating temperature is dependent on the feedback device installed. Motors with resolver feedback can be specially configured to operate down to -40°C.

Optional 24VDC holding brakes are available.

Optional IP65 sealing is available

RoHS compliant.

CE marked.

UL Recognized Component for US and Canada.

# **GMR4900 SERIES ENVIRONMENTAL CONDITIONS**

Storage Temperature:  $-20^{\circ}\text{C}$  to  $70^{\circ}\text{C}$ 

Operating Temperature: Standard: -20°C to 40°C without derating, derate torque 10% per 10°C above 40°C

Special: -40°C to 40°C without derating, derate torque 10% per 10°C above 40°C

**Humidity:** 5% to 95% relative humidity, non-condensing

Altitude: Up to 1000m without derating, derate torque 10% per 1000m above 1000m

## **GMR4900 SERIES SELECTION TABLE**

 $\rm K_T = Torque\ Constant\ ullet\ K_V = BEMF = Volts/1000\ RPM\ ullet\ L_A = Inductance$ 

Model Number		@ Max eed	Cont.	Stall R	ating	Peak	Stall Ro	ating	K	т	R <sub>A</sub>	L	RPM	K <sub>v</sub>	Armatur	e Inertia
	HP	KW	Lb-in	Nm	Amps	Lb-in	Nm	Amps	Lb-in/A	Nm/A	Ω	mH	Max	V/Krpm	Lb-in-sec <sup>2</sup>	Kg-m²
GMR4910-26	1.21	0.903	19	2.15	8.6	95.0	10.75	43.0	2.22	0.25	0.8	2.30	4000	26	0.00600	0.000678
GMR4910-37	1.12	0.835	19	2.15	5.9	95.0	10.75	29.5	3.20	0.36	1.4	4.29	3700	37	0.00600	0.000678
GMR4920-38	2.06	1.537	35	3.95	10.8	175.0	19.75	54.0	3.23	0.36	0.5	1.49	3700	38	0.00900	0.001017
GMR4920-68	1.17	0.873	35	3.95	6.0	175.0	19.75	30.0	5.80	0.66	1.9	5.26	2100	68	0.00900	0.001017
GMR4940-38	3.02	2.253	50	5.65	15.2	250.0	28.25	76.0	3.28	0.37	0.3	1.00	3800	38	0.01500	0.001695
GMR4940-78	1.34	0.999	50	5.65	6.6	250.0	28.25	33.0	6.60	0.75	2.2	10.80	1700	78	0.01500	0.001695
GMR4950-35	4.13	3.081	65	7.34	21.4	325.0	36.70	107.0	3.04	0.34	0.2	0.65	4000	35	0.01600	0.001808
GMR4950-57	2.58	1.924	65	7.34	13.4	325.0	36.70	67.0	4.87	0.55	0.6	1.64	2500	57	0.01600	0.001808

**NOTE:** All ratings based on a 40°C ambient temperature with the motor face mounted to a 12" x 12" x 1/2" aluminum heatsink.

## **GMR4900 SERIES BRAKE OPTION**

Motor Frame Size	Extension	Tor	Torque		Current	Resistance	Inductance
Motor Fruitie Size	in. (mm)	Lb-in	Nm	Watts	A	Ω	mH
GMR4900	2.19 (56)	160	18	24	1.0	24	100

#### Note:

Brakes are optional. All brakes require 24 VDC input voltage. The values for "Extension" represent the nominal maximum length that the brake will add to the motor. For some models, the extension will be less. Please contact one of our sales engineers for the exact values.

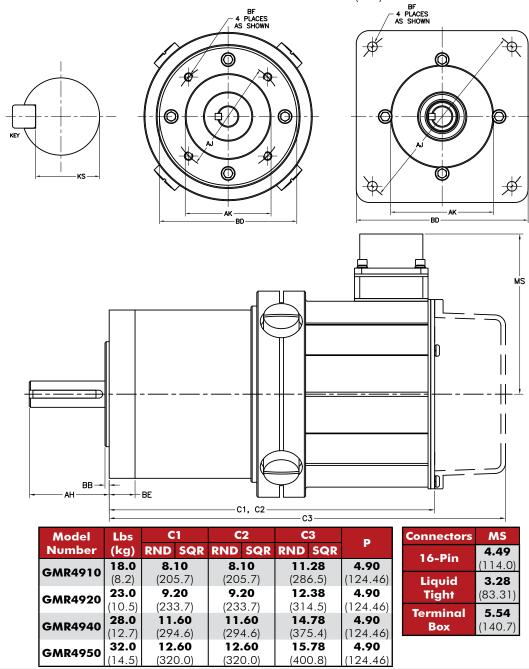
### **SHAFT LOAD RATINGS**

Motor Frame Size	Radial SI	naft Load	Axial Shaft Load		
Motor Frame Size	Lbs	N	Lbs	N	
GMR4900	100	440	40	180	

**Note:** This table is for general guidance only. Shaft load ratings are approximations and will vary with shaft diameter, the location of the load on the shaft, speed (RPM), bearings, and more. The values in the table are for a load located 1" (25.4 mm) from the mounting face of the motor and at 3000 RPM.

## **GMR4900 SERIES DIMENSIONS**

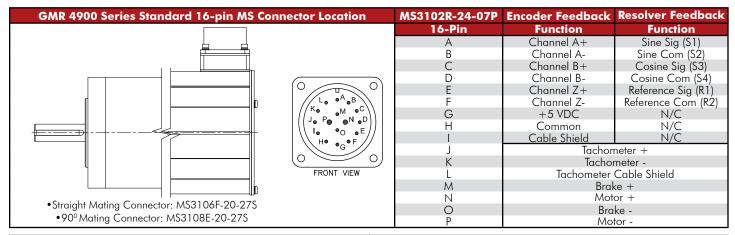
C1 = Bare Motor, C2 = Motor with Tachometer or Encoder, C3 = Motor with Tachometer and Encoder. Note: Dimensions are in inches (mm)

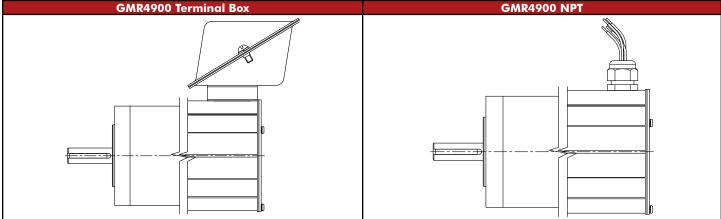


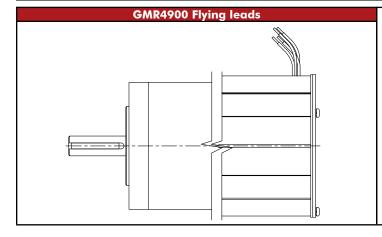
Flange	Shaft			Flange/Face				Mou	Mounting Hole		
Type	АН	U (MAX)	KEY	KS	AJ	AK	ВВ	BD	BE (MAX)	BF Dia.	Тар
Round	<b>1.90</b> (48.26)	<b>0.6250</b> (15.88)	0.188 SQ. X 1.50	0.507- 0.517	<b>3.500</b> (82.55)	<b>2.498</b> (63.45)	<b>0.10</b> (2.54)	<b>4.00</b> (101.60)	<b>0.62</b> (15.7)	-	1/4-20 <b>▼.50</b>
Square M1	<b>1.90</b> (48.26)	<b>0.6250</b> (15.88)	0.188 SQ. X 1.50	0.507- 0.517	<b>4.950</b> (125.73)	<b>2.187</b> (55.55)	<b>0.06</b> (1.52)	<b>4.25</b> (107.95)	<b>0.44</b> (11.18)	<b>0.281</b> (7.14)	THRU
Square M2	<b>1.90</b> (48.26)	<b>0.6250</b> (15.88)	0.188 SQ. X 1.50	0.507- 0.517	<b>5.741</b> (145.82)	<b>3.000</b> (76.20)	<b>0.10</b> (2.54)	<b>5.00</b> (127.00)	<b>0.44</b> (11.18)	<b>0.281</b> (7.14)	THRU
Square M3	<b>1.90</b> (48.26)	<b>0.6250</b> (15.88)	0.188 SQ. X 1.50	0.507- 0.517	<b>5.875</b> (149.23)	<b>4.500</b> (114.30)	<b>0.10</b> (2.54)	<b>5.00</b> (127.00)	<b>0.44</b> (11.18)	-	3/8-16 THRU
NEMA 42	<b>1.32</b> (33.5)	<b>0.6250</b> (15.88)	0.188 SQ. X 1.50	0.507- 0.517	<b>4.950</b> (125.73)	<b>2.187</b> (55.55)	<b>0.06</b> (1.52)	<b>4.25</b> (107.95)	<b>0.48</b> (12.19)	<b>0.281</b> (7.14)	THRU
NEMA 56C	<b>2.06</b> (52.32)	<b>0.6250</b> (15.88)	0.188 SQ. X 1.50	0.507- 0.517	<b>5.875</b> (149.23)	<b>4.500</b> (114.30)	<b>0.09</b> (2.29)	<b>6.50</b> (165.10)	<b>0.44</b> (11.18)	-	3/8-16 THRU

## **CONNECTORS & PIN-OUT INFORMATION**

With a positive voltage applied to the red motor lead (Motor +) with respect to the black motor lead (Motor -), the motor drive shaft will turn in the **counter-clockwise** direction as viewed from the shaft end.

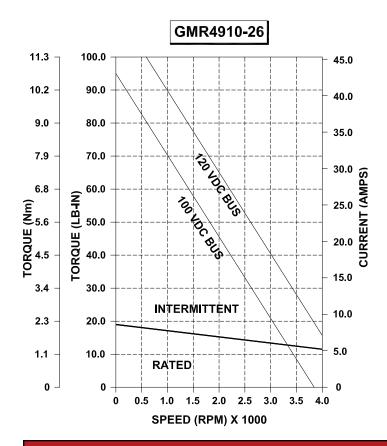






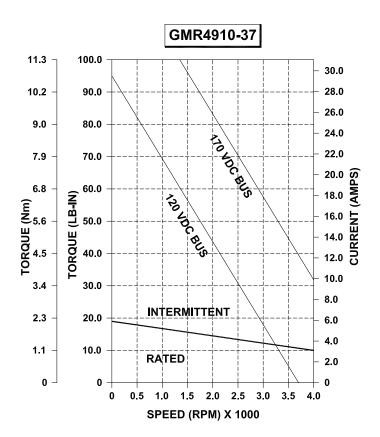
**Glentek's GMR4900 Series** offer Special mounting options please contact a Gletnek Sales Engineer for detailed information.

## **GMR4910-26 PERFORMANCE DATA**



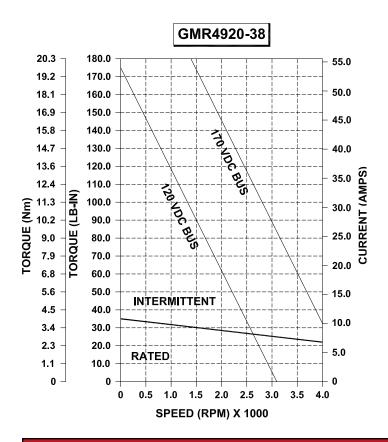
Dower @ May Speed	HP	1.21
Power @ Max Speed	KW	0.903
	Lb-in	19
Cont. Stall Rating	Nm	2.15
	Amps	8.6
	Lb-in	95.0
Peak Stall Rating	Nm	10.75
	Amps	43.0
Tayaya Canatant	Lb-in/A	2.22
Torque Constant	Nm/A	0.25
Resistance	Ohms	0.8
Inductance	mH	2.30
Maximum Speed	RPM	4000
Back EMF	V/Krpm	26
Armature Inertia	Lb-in-sec <sup>2</sup>	0.00600
Armaiure ineriia	Kg-m²	0.000678

#### **GMR4910-37 PERFORMANCE DATA**



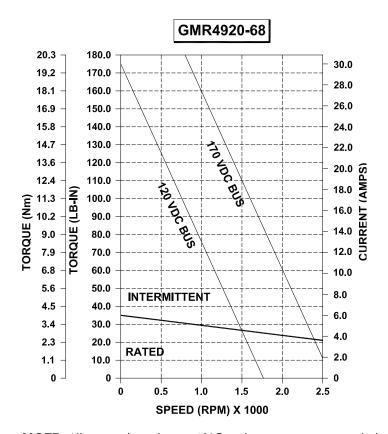
Dawer @ May Speed	HP	1.12
Power @ Max Speed	KW	0.835
	Lb-in	19
Cont. Stall Rating	Nm	2.15
	Amps	5.9
	Lb-in	95.0
Peak Stall Rating	Nm	10.75
	Amps	29.5
Torque Constant	Lb-in/A	3.20
iorque constant	Nm/A	0.36
Resistance	Ohms	1.4
Inductance	mH	4.29
Maximum Speed	RPM	3700
Back EMF	V/Krpm	37
Armature Inertia	Lb-in-sec <sup>2</sup>	0.00600
Armaiore merna	Kg-m²	0.000678

## **GMR4920-38 PERFORMANCE DATA**



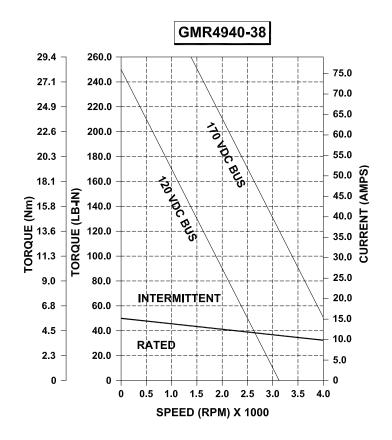
Dawer @ Mary Success	HP	2.06
Power @ Max Speed	KW	1.537
	Lb-in	35
Cont. Stall Rating	Nm	3.95
	Amps	10.8
	Lb-in	175.0
Peak Stall Rating	Nm	19.75
	Amps	54.0
Torque Constant	Lb-in/A	3.23
iorque constant	Nm/A	0.36
Resistance	Ohms	0.5
Inductance	mH	1.49
Maximum Speed	RPM	3700
Back EMF	V/Krpm	38
Armature Inertia	Lb-in-sec <sup>2</sup>	0.00900
Armaiore merna	Kg-m²	0.001017

#### **GMR4920-68 PERFORMANCE DATA**



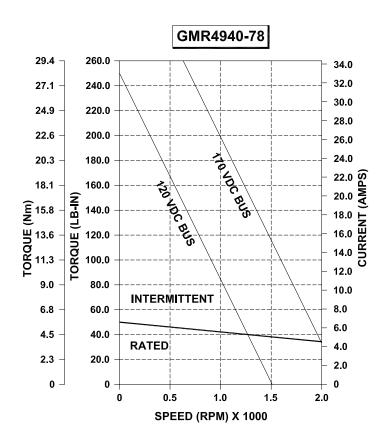
Power @ Max Speed	HP	1.17
rower @ max speed	KW	0.873
	Lb-in	35
Cont. Stall Rating	Nm	3.95
	Amps	6.0
	Lb-in	175.0
Peak Stall Rating	Nm	19.75
	Amps	30.0
Torque Constant	Lb-in/A	5.80
lorque constant	Nm/A	0.66
Resistance	Ohms	1.9
Inductance	mH	5.26
Maximum Speed	RPM	2100
Back EMF	V/Krpm	68
Armature Inertia	Lb-in-sec <sup>2</sup>	0.00900
Armaiore merna	Kg-m²	0.001017

## **GMR4940-38 PERFORMANCE DATA**



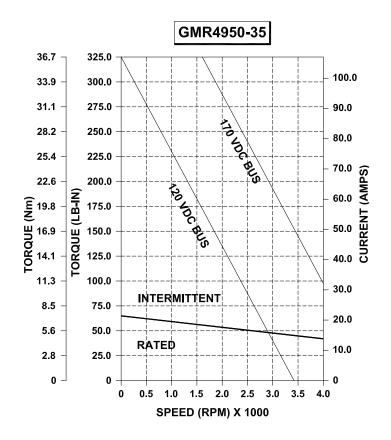
Power @ Max Speed	HP	3.02
Fower @ Max Speed	KW	2.253
	Lb-in	50
Cont. Stall Rating	Nm	5.65
	Amps	15.2
	Lb-in	250.0
Peak Stall Rating	Nm	28.25
	Amps	76.0
Torque Constant	Lb-in/A	3.28
iorque constant	Nm/A	0.37
Resistance	Ohms	0.3
Inductance	mH	1.00
Maximum Speed	RPM	3800
Back EMF	V/Krpm	38
Armature Inertia	Lb-in-sec <sup>2</sup>	0.01500
Armaiore merna	Kg-m²	0.001695

## **GMR4940-78 PERFORMANCE DATA**



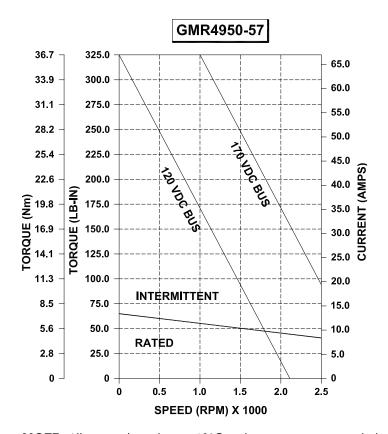
Dower @ May Speed	HP	1.34
Power @ Max Speed	KW	0.999
	Lb-in	50
Cont. Stall Rating	Nm	5.65
	Amps	6.6
	Lb-in	250.0
Peak Stall Rating	Nm	28.25
	Amps	33.0
Torque Constant	Lb-in/A	6.60
Torque Constant	Nm/A	0.75
Resistance	Ohms	2.2
Inductance	mH	10.80
Maximum Speed	RPM	1700
Back EMF	V/Krpm	78
Armature Inertia	Lb-in-sec <sup>2</sup>	0.01500
Armaiore mema	Kg-m²	0.001695

## **GMR4950-35 PERFORMANCE DATA**



Dower @ May Speed	HP	4.13
Power @ Max Speed	KW	3.081
	Lb-in	65
Cont. Stall Rating	Nm	7.34
	Amps	21.4
	Lb-in	325.0
Peak Stall Rating	Nm	36.70
	Amps	107.0
Torque Constant	Lb-in/A	3.04
lorque constant	Nm/A	0.34
Resistance	Ohms	0.2
Inductance	mH	0.65
Maximum Speed	RPM	4000
Back EMF	V/Krpm	35
Armature Inertia	Lb-in-sec <sup>2</sup>	0.01600
Armaiore merria	Kg-m²	0.001808

## **GMR4950-57 PERFORMANCE DATA**



Dower @ May Speed	HP	2.58
Power @ Max Speed	KW	1.924
	Lb-in	65
Cont. Stall Rating	Nm	7.34
	Amps	13.4
	Lb-in	325.0
Peak Stall Rating	Nm	36.70
	Amps	67.0
Tayaya Canatant	Lb-in/A	4.87
Torque Constant	Nm/A	0.55
Resistance	Ohms	0.6
Inductance	mH	1.64
Maximum Speed	RPM	2500
Back EMF	V/Krpm	57
Armature Inertia	Lb-in-sec <sup>2</sup>	0.01600
Armaiure inerna	Kg-m²	0.001808

#### **GMR4900 SERIES MODEL NUMBERING**

This section explains the model numbering system for Glentek's GMR4900 Series DC Brush Servo Motors. The model numbering system is designed so that you, our customer, will be able to quickly and accurately create the model number for the drive that best suits your requirements. Please complete the drive configuration code you require using the information on this page. After completing your model number, please contact a Gletnek Sales Engineer to confirm that the model number you have created is correct.

